THE TEMPERATURE DEPENDENCE OF THE PARAMETERS OF NON-LINEAR STRESS-STRAIN RELATIONS FOR CARBON-EPOXY COMPOSITES

TEMPERATURNA ODVISNOST PARAMETROV NELINEARNE ODVISNOSTI NAPETOST-DEFORMACIJA ZA KOMPOZITE OGLJIKOVO VLAKNO-EPOKSI

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This work focuses on the identification of the parameters of stress-strain relations for a unidirectional, continuous-fiber carbon-epoxy composite under tensile loading at various temperatures. Simple tensile tests of thin strips with various fiber orientations were performed. The identification of the parameters for the chosen non-linear stress-strain relations is obtained at each temperature for which the experiment is performed and the strength is determined. The failure analysis for the determination of the first failure with the use of Puck’s action-plane concept is performed, and the tensile and shear strength are investigated. The identification process with the use of a combination of the mathematical optimization method and a finite-element-element analysis is described with the necessary details. The temperature dependence of the parameters is also investigated.

Key words: composite, non-linear, carbon, epoxy, tensile, FEA, temperature

1 INTRODUCTION

The aim was to investigate the temperature dependence of the parameters of non-linear stress-strain relations for a unidirectional carbon-epoxy composite with the use of a finite-element (FE) analysis. The elasticity parameters and strengths were found from the comparison of the FE analysis and experimental results for simple tension tests of thin carbon-epoxy strips with dimensions 150 mm × 14.5 mm × 1.08 mm. Specimens with three fiber directions were used. The fiber directions formed angles of 0°, 45° and 90° with the direction of the loading force. The tensile tests were performed at 25 °C, 50 °C, 75 °C and 100 °C.

Two types of non-linear stress-strain relations are presented. Their capabilities for prediction of the behavior of the composite material loaded with simple tension at various temperatures were investigated. The strengths of the material were investigated with the use of Puck’s failure criterion 2.

2 NON-LINEAR STRESS-STRAIN RELATIONS

Several types of stress-strain relations exist. A linear stress-strain relation is the simplest way to describe the behavior of a composite material 2. Unfortunately, it cannot describe the non-linear slope of the curves obtained from the tensile tests.

The next type is the non-linear stress-strain relation proposed in 1, which takes into account a non-linear relationship between the shear stress and the strain only, and is generalized in 3. This relation can be written in a material axes coordination system L (longitudinal – fiber direction), T (transverse direction) for the state of plane stress in the form

\[
\begin{bmatrix}
\varepsilon_L \\
\varepsilon_T \\
\gamma_{LT}
\end{bmatrix} =
\begin{bmatrix}
S_{11} & S_{12} & 0 \\
S_{21} & S_{22} & 0 \\
0 & 0 & S_{66}
\end{bmatrix}
\begin{bmatrix}
\sigma_L \\
\sigma_T \\
\tau_{LT}
\end{bmatrix}
\]

where

\[
S_{11} = \frac{1}{E_L}
\]

\[
S_{22} = \frac{1}{E_T}
\]

\[
S_{12} = -\frac{v_{LT}}{E_L}
\]

\[
F_{LT} = \frac{1}{E_T}
\]

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The strains are expressed as polynomial functions of the stresses and the relation contains 7 independent parameters that can be sorted as linear parameters (Young’s moduli) $E_L, E_T, G_{LT}$, Poisson’s ratio $\nu_{LT}$ and the non-linear parameters $S_{11}, S_{22}$ and $S_{666}$. The orders of the polynomials are predetermined and suitable for the tests performed at normal temperatures. The whole relation (R1) has to be inverted for proper use in the FE software. The Newton iteration method is used in the work to find the roots of the equation

$$f(\sigma_L, \sigma_T, \tau_{LT}) = S\sigma - \epsilon = 0$$

where $S$ is the stress-strain matrix, $\sigma$ is the stress vector and $\epsilon$ is the strain vector.

The stress-strain relation, which takes into consideration the non-linear behavior of the composite material and where the stresses are explicit functions of strains, can be expressed in the form

$$\begin{bmatrix} \sigma_L \\
\sigma_T \\
\tau_{LT} \end{bmatrix} = \begin{bmatrix} E_L & \frac{E_L}{1 - \nu_{LT}^2} & \frac{E_L}{\nu_{LT}} \\
\frac{E_L}{1 - \nu_{LT}^2} & E_T & \frac{E_T}{\nu_{LT}} \\
\frac{E_L}{\nu_{LT}} & \frac{E_T}{\nu_{LT}} & G_{LT} \end{bmatrix} \begin{bmatrix} \epsilon_L \\
\epsilon_T \\
\gamma_{LT} \end{bmatrix}$$

(9)

where Ramberg-Osgood-based equations provide expressions for the tangent lamina stiffnesses

$$E_L = \frac{E_L^0}{1 + \left( \frac{\epsilon_L^0}{\epsilon_L} \right)^{n_L - 1}}$$

(10)

$$E_T = \frac{E_T^0}{1 + \left( \frac{\epsilon_T^0}{\sigma_T^0} \right)^{n_T - 1}}$$

(11)

$$G_{LT} = \frac{G_{LT}^0}{1 + \left( \frac{\gamma_{LT}^0}{\tau_{LT}} \right)^{n_{LT} - 1}}$$

(12)

and the relation between the Poisson’s ratios is considered as

$$\nu_{TL} = \nu_{LT} \frac{E_T^0}{E_L^0}$$

(13)

3 IDENTIFICATION OF THE ELASTICITY PARAMETERS

The identification of the elasticity parameters is the first step in the identification process. The method used for the identification of the elasticity parameters, which combines the material axis and the off-axis tensile tests, the FE analysis and the mathematical optimization method will be described in the following paragraph.

Non-linear stress-strain relations have to be implemented into the FE software first. The number of elements in the FE models for the calculation of the force-displacement diagrams has to be reduced as much as possible. The reduction of the number of elements is necessary for the reduction of the time consumption during the optimization cycles. The next step is to propose the residual function that represents the difference between the numerical and the experimental
results at the given optimization step, and which is minimized. The function is proposed as

\[ r = \sum_{\theta} \left[ F_{\text{exp}}(\theta, p) - F_{\text{num}}(\theta, p) \right]^2 \]

where \( \theta \) is the fiber angle, \( r(\theta) \) is the residual of the force-displacement diagram for the fiber angle \( \theta \), which had values 0°, 15°, 30°, 45°, 60°, 75° and 90°; \( p \) is the displacement where the residual is calculated; \( F_{\text{num}}(\theta, p) \) is the calculated force corresponding to the displacement \( p \) of the strip with the fiber angle \( \theta \); \( F_{\text{exp}}(\theta, p) \) is the experimentally measured force corresponding to the displacement \( p \) of the strip with the fiber angle \( \theta \) and \( \max_{p} F_{\text{exp}}(\theta, p) \) is the maximum force measured as a response of the strip with a fiber angle \( \theta \), used as a normalization coefficient.

It should be noted that the Poisson’s ratio \( \nu_{LT} \) has to be identified with a special, separate test and, therefore, it will not be investigated in this paper, and its value is taken as \( \nu_{LT} = 0.28 \). The tests, probably a biaxial test able to precisely describe the potential strain dependence of the Poisson’s \( \nu_{LT} \) ratio, and a further analysis of the influence of the temperature on the Poisson’s ratio \( \nu_{LT} \) will be performed in the near future.

The flow chart of the whole automated process of the identification of the elasticity parameters is shown in Figure 3.

4 IDENTIFICATION OF THE STRENGTHS

Once the elasticity parameters are identified, the identification of the strengths can be performed. The failure criterion used in the strengths identification process is Puck’s action-plane concept. For more about the criterion, see 4–6. Once the tensile test is performed, only the tensile \( X^T \), \( Y^T \) and the shear \( S^T \) strengths can be identified. The identification of the strengths is performed with the use of a minimized function, which is proposed as the sum of the errors between the average of the measured ultimate forces and the calculated ultimate force for each fiber angle

\[ r = \sum_{\theta} \left[ F_{\text{exp}}(\theta) - F_{\text{num}}(\theta) \right] \]

where \( \theta \) is the fiber angle, \( F_{\text{exp}}(\theta) \) is the average of the measured ultimate forces for the given fiber angle \( \theta \) and \( F_{\text{num}}(\theta) \) is the calculated ultimate force for the given fiber angle \( \theta \). The flow chart of the identification process of the strengths is shown in Figure 4.

Let us briefly describe the flow chart in Figure 4. At the start of the identification process the initial displacement increment \( \Delta u_{\text{init}} \) is prescribed. The FE analysis is the next step. Subsequently, the failure analysis is performed and the failure indices (\( FIs \)) are calculated. These indices represent the level of the load with respect to the strength of the material. If the \( FI \) reaches one, the material is damaged. Once the \( FIs \) are calculated, the decision process that results in the displacement increment that is applied in the next step is performed. The constant \( k_e \) is used to improve the convergence speed. Once the matrix-failure index \( F_{\text{M}} \) or the fiber-failure index \( F_{\text{F}} \) reaches \( 1 \) (with the tolerance \( \varepsilon_{F} \)) the identification process ends.

5 RESULTS

The identified elasticity parameters using the relationship (1) are shown in Table 1. The decreasing tendency of the linear parameters and the increasing tendency of the non-linear part of the parameters with increasing temperature are evident. The exceptions are the shear modulus, which increases with the temperature 100 °C, and the Young’s modulus for the fiber direction \( E_L \), which remains constant.
Table 1: Elasticity parameters used in (1)
Tabela 1: Parametri elastičnosti uporabljeni v (1)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>25 °C</th>
<th>50 °C</th>
<th>75 °C</th>
<th>100 °C</th>
</tr>
</thead>
<tbody>
<tr>
<td>$E_l$/GPa</td>
<td>111.58</td>
<td>111.69</td>
<td>111.47</td>
<td>111.59</td>
</tr>
<tr>
<td>$E_t$/GPa</td>
<td>8.48</td>
<td>7.30</td>
<td>6.50</td>
<td>4.77</td>
</tr>
<tr>
<td>$G_{tt}$/GPa</td>
<td>3.98</td>
<td>4.10</td>
<td>3.83</td>
<td>8.69</td>
</tr>
<tr>
<td>$(S_{111·10^{-22}})$/Pa$^{-2}$</td>
<td>-4.66</td>
<td>-4.67</td>
<td>-4.65</td>
<td>-4.49</td>
</tr>
<tr>
<td>$(S_{222·10^{-19}})$/Pa$^{-2}$</td>
<td>3.46</td>
<td>3.78</td>
<td>5.79</td>
<td>68.47</td>
</tr>
<tr>
<td>$(S_{666·10^{-26}})$/Pa$^{-3}$</td>
<td>12.75</td>
<td>21.97</td>
<td>58.93</td>
<td>442.27</td>
</tr>
</tbody>
</table>

Table 2 shows the identified parameters that were obtained by using relation (9).

Table 2: Elasticity parameters used in (9)
Tabela 2: Parametri elastičnosti uporabljani v (9)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>25 °C</th>
<th>50 °C</th>
<th>75 °C</th>
<th>100 °C</th>
</tr>
</thead>
<tbody>
<tr>
<td>$E_l^0$/GPa</td>
<td>106.26</td>
<td>107.71</td>
<td>106.19</td>
<td>107.51</td>
</tr>
<tr>
<td>$E_t^0$/GPa</td>
<td>8.25</td>
<td>7.15</td>
<td>6.38</td>
<td>4.35</td>
</tr>
<tr>
<td>$G_{tt}^0$/GPa</td>
<td>3.44</td>
<td>3.27</td>
<td>3.00</td>
<td>2.34</td>
</tr>
<tr>
<td>$\varepsilon_l^0$</td>
<td>1.44</td>
<td>0.72</td>
<td>1.49</td>
<td>0.78</td>
</tr>
<tr>
<td>$\sigma_t^0$/MPa</td>
<td>176.52</td>
<td>147.00</td>
<td>129.52</td>
<td>33.64</td>
</tr>
<tr>
<td>$\tau_{tt}^0$/MPa</td>
<td>56.66</td>
<td>38.80</td>
<td>31.48</td>
<td>17.28</td>
</tr>
<tr>
<td>$n_l$</td>
<td>0.56</td>
<td>0.65</td>
<td>0.56</td>
<td>0.64</td>
</tr>
<tr>
<td>$n_t$</td>
<td>1.38</td>
<td>1.61</td>
<td>1.35</td>
<td>1.33</td>
</tr>
<tr>
<td>$n_{tt}$</td>
<td>1.44</td>
<td>1.83</td>
<td>1.53</td>
<td>1.89</td>
</tr>
</tbody>
</table>

The initial Young’s modulus in the fiber direction is constant, while the rest of the initial moduli show a decreasing tendency. The asymptotic strain level does not show any dependence on the temperature. The asymptotic stress levels decrease with the increasing temperature. The values of the shape parameters are oscillating. Figure 5 shows the temperature dependence of the residual (14). The increase of the residuals of the relation (1) with the increase of the temperature is obvious and the better capability of relation (9) is evident.

Table 3: Strength identified with the use of (1)
Tabela 3: Trdnosti določene z uporabo (1)

<table>
<thead>
<tr>
<th>Strength</th>
<th>25 °C</th>
<th>50 °C</th>
<th>75 °C</th>
<th>100 °C</th>
</tr>
</thead>
<tbody>
<tr>
<td>$X_t$/MPa</td>
<td>1937.2</td>
<td>1937.0</td>
<td>1937.1</td>
<td>1937.0</td>
</tr>
<tr>
<td>$Y_t$/MPa</td>
<td>36.7</td>
<td>38.2</td>
<td>32.8</td>
<td>16.9</td>
</tr>
<tr>
<td>$S_t$/MPa</td>
<td>58.4</td>
<td>49.3</td>
<td>39.2</td>
<td>73.6</td>
</tr>
</tbody>
</table>

Table 4: Strengths identified with the use of (9)
Tabela 4: Trdnosti izračunane z uporabo (9)

<table>
<thead>
<tr>
<th>Strength</th>
<th>25 °C</th>
<th>50 °C</th>
<th>75 °C</th>
<th>100 °C</th>
</tr>
</thead>
<tbody>
<tr>
<td>$X_t$/MPa</td>
<td>1937.0</td>
<td>1937.0</td>
<td>1937.1</td>
<td>1937.0</td>
</tr>
<tr>
<td>$Y_t$/MPa</td>
<td>36.4</td>
<td>38.2</td>
<td>32.8</td>
<td>16.9</td>
</tr>
<tr>
<td>$S_t$/MPa</td>
<td>61.0</td>
<td>49.3</td>
<td>39.2</td>
<td>73.6</td>
</tr>
</tbody>
</table>

The temperature independence of the strength $X_t$ is visible from Tables 3 and 4. Also, the decreasing tendency of the strength $Y_t$ and $S_t$ is evident, except for the high value of the shear strength for 100 °C. The differences between the sums of the errors between the ultimate forces are negligible.

6 CONCLUSION

The capabilities of two types of non-linear stress-strain relations were investigated. The better suitability of the stress-strain relation based on the Ramberg-Osgood equations was proven. The influence of the viscoelasticity was neglected in the work.

The Puck’s failure criterion was used for the failure analysis and the prediction of the strengths. It provides acceptable results for temperatures up to 75 °C.

Acknowledgements

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7 REFERENCES


Figure 5: Sum of the residuals calculated with the use of (14) ($\times$ – (1), $\circ$ – (9))

Slika 5: Vsota rezidualov, izračunana s uporabo (14) ($\times$ – (1), $\circ$ – (9))