1 INTRODUCTION

Milling is the key manufacturing operation for the successful machining of fiber-reinforced plastic parts, which ensures dimensional and qualitative requirements. Milling is used, as a rule, as an edge-trimming operation, or a slotting/routing process to produce complex contours.

Composite materials such as carbon fiber-reinforced plastics (CFRPs) are heterogeneous materials composed of dissimilar constituents, where the resulting mechanical properties are more than the sum of the characteristics of the individual components. A plastic matrix of CFRPs is reinforced by carbon fibers entirely, resulting in a high specific strength and stiffness throughout the lifetime of the components, together with electrical and magnetic resistance. This makes them interesting for applications in the automotive and aircraft industries, in railway and ship building, medical applications and the space industry.\(^1,^2\)

CFRP composites replace traditional metallic materials; however, their machinability is fundamentally different and the cutting mechanism is still under investigation. The machining properties are influenced by the heterogeneity and anisotropy of the composite material. The mechanical properties of the matrix are strongly
temperature dependent, while the carbon fibers can withstand temperatures up to 3000 °C, and during machining cause considerable tool wear. Machining CFRPs brings with it certain difficulties, such as layer delaminations, fiber pull-out, uncut fibers, degradation and burning of the plastic matrix. Tool manufacturers and scientists recommend carbide tools with a polycrystalline diamond (PCD) coating for CFRP material machining. These tools ensure high productivity with a sufficient tool life. Unfortunately, the cost of PCD tools is six times higher than uncoated tools, whereas tool life is only three times longer. End mills usually have a very special design suitable for the milling of CFRPs. Helical end mills with two flutes are suitable for rigid or back-supported parts. Compression end mills with two sets of left-hand and right-hand flutes limit the delamination and burrs on the cut edges. Furthermore, the machining of flexible parts by multi-tooth end mills eliminates the cutting force along the Z-axis, thereby reducing the deflection and vibration of the part. In-between are helical mills with a chip-breaker geometry that shears fibers and shortens chips with the simultaneous reduction of vibrations.

In this work we compare the performance of end mills on the resulting surface quality, dimensional accuracy and cutting forces in the slotting and side milling of CFRPs.

2 EXPERIMENTAL PROCEDURE

The composite samples used in the experimental investigation were produced by vacuum infusion technology. The carbon fiber and the epoxy were supplied by KORDCARBON CZ. The fabric was Toray HS 3K 200 tex, a balanced twill bidirectional (0–90°) weave and 380 μm thick. The epoxy used in the fabrication was the commercially available Havel L285 epoxy system.

Fourteen layers of fabric were used to fabricate the work samples with an average thickness of 4 mm. Overall, the CFRP composite average flexure strength was 501 MPa, the modulus of elasticity was 43,300 GPa and the tensile strength was 378 MPa.

The experiment was carried out by using eight carbide end mills acquired from different producers (SECO, WNT, KTOOLS). The required tool cutting diameter was 6 mm. In this article the end mills are referred to as T1-T8 and were concerned for special applications such as the milling of composites with a wide range of compositions. Their geometry is summarized in Table 1. Except for the T4 tool, the end mills were coated to withstand the machining of a highly abrasive work material.

A CNC milling machine C-442 HWT with a 1.0-kW spindle power and high-speed spindle of 416.16 Hz was used to perform the experiments. Part of the program was created to ensure the repeatability and accuracy of the experiment. The machining was divided into two consecutive methods, first slot milling (Figure 1a) and next upcut side milling (Figure 1b) of the CFRP work material. The machining conditions are given in Table 2 for both methods. A coolant was not used and the tool cutting length was 150 mm in both methods. A tool-wear evaluation was carried out at the end of every set of experiments. First, each tool was milling a slot and subsequently a side of work material, so that the tool displacement towards the bottom surface of the work material was 2 mm.

<table>
<thead>
<tr>
<th>Method</th>
<th>Cutting speed (v_c) (m/min)</th>
<th>Feed rate (v_f) (mm/min)</th>
<th>Depth of cut (a_p) (mm)</th>
<th>Width of cut (a_e) (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Slot milling</td>
<td>100</td>
<td>550</td>
<td>1.25</td>
<td>(a_e = D)</td>
</tr>
<tr>
<td>Side milling</td>
<td>100</td>
<td>550</td>
<td>2.0</td>
<td>4.0</td>
</tr>
</tbody>
</table>

Cutting forces were measured on the strain-gauge dynamometer in the direction of the feed-rate vector (force \(F_f\)) and perpendicularly to \(F_f\) (force \(F_{fn}\)). The signal from dynamometer was processed by a Spider8 data-acquisition system and the evaluations were made through a PC with Conmes Spider software, as illustrated in Figure 2.

The dimensional accuracy of the machined slot was evaluated using a Mitutoyo caliper. The surface quality was measured with a portable surface-roughness tester Mitutoyo SJ-301, according to ISO 4287 on the high-
lighted areas at the bottom of the slot (Figure 1a) and the side surface (Figure 1b). The measurements repeated were 15 times at different surface locations in the direction of the feed-rate vector that was identified as the direction of highest roughness. The roughness parameter $R_a$ was considered as an evaluation parameter for the surface quality according to ISO.

3 RESULTS AND DISCUSSION

3.1 Cutting forces

All the force measurements were worth a maximum of 4.86% of variance. The results were graphically summarized in Figures 3 and 4. There is a significant difference between the end mills, moreover not the only one is suitable both as side and slot milling. Tool T6 with right- and left-hand spirals reached the lowest values $F_f$ when slot milling (Figure 3) and the second best value as for T4 tool without coating. Higher values of $F_f$ and $F_fn$ were achieved by the same T3 tool with the coating. This may be due to increased adhesion of work material to the PCD coating material.

Tools T1, T3, T8 keep along the average. Conversely, the highest values of $F_f$ achieved tool T2 and T7, although with different flute geometries, but with the same helix angle of 10°, despite the normal force $F_{fn}$ was the lowest one. The helix angle probably improves the chip removal at the bottom of the slot; however, the tool is more power loaded in the feed direction. In the case of higher cutting depths we can expect a higher tool bend, but without a buckling effect.

When side milling, the non-significant $F_{fn}$ force was not evaluated, yet was mentioned in Figure 4. The force $F_f$ is more than 2 times higher than when slot milling. The smallest $F_f$ value comes from the T4 tool without coating, the worst was the T6 tool with a right- and left-hand hand spiral. The reason for this may be in the compression effect of contra-rotating spirals, becoming for these tools. Although the flutes’ geometry for the T1, T2, T5 and T8 tools was dissimilar, the feed-force characteristics were almost identical and quite balanced.

3.2 Surface roughness

The dynamometric investigation was followed by surface-roughness measurements of the $R_a$ parameter.
The results are shown in Figure 5 for the side and slot milling.

The lowest average value of $R_a = 1.38\pm0.40 \mu m$ was on the side surface made by the uncoated T4 tool and the same value $R_a = 1.38\pm0.29 \mu m$ is at the bottom of the slot by the T8 tool. The T5 tool had the highest and most unsatisfactory effect for side milling, where the roughness value was $R_a = 6.19\pm1.57 \mu m$. It is the only tool with an upcut spiral in the experiment and is actually a production tool recommended for rough machining. Approximately half values of $R_a = 3.45\pm1.30 \mu m$, but highest for slot milling, was made with the cross-pitched T7 tool with a 0° rake angle.

### 3.3 Dimensional accuracy

Since end mills should have a 6 mm diameter, it was expected that the resulting dimension of the slot would be given with a certain accuracy close to that value. As it turned out, this was not entirely true for slot milling of CFRP work material, as can be seen in Figure 6.

In most cases, the resulting dimension of the slot is smaller than the desired nominal size. On the one hand, it could be given by the true tool diameter (Table 1) that was smaller than the producer specification. In contrast, for the T5 tool with an upcut spiral we found that the slot was about 0.13 mm wider. This excludes the possibility that a smaller tool diameter was made on purpose, taking into account the CFRP material’s behavior. Finally, the T8 tool made it possible to achieve a superior slot accuracy, but otherwise lagged behind in terms of cutting efficiency and surface quality.

### 4 CONCLUSIONS

In this work the cutting performance of the end mills in the CFRPs milling has been presented, taking into account the force, surface roughness and dimensional measurements. After the testing of eight end mills several conclusions can be drawn:

- an upcut spiral can cause considerably worse surface quality together with an increment of the slot dimension,
- PCD-coated tools for CFRPs machining has a lower cutting efficiency due to a different friction characteristic than the uncoated tools,
- tools with left-hand and right-hand spirals recommended for side milling, result in up to twice the cutting force,
- to ensure compliance with the required dimensions, accuracy and stability it is necessary to include an offset (by part program, cutting conditions, thermal field) for the CFRPs tool individually.

### 5 REFERENCES

11. P. Masek, P. Zeman, Effective milling of composites with thermoplastic matrix, MM Prumyslove spektrum, 6 (2013), 60–64

Figure 6: Dimensional accuracy of the width of the slot
Slika 6: Dimenzijska natančnost širine utora

Table 1