The presented work is aimed at a demonstration of modern radiological methods for an investigation of the deformation behaviour of bone scaffolds. Bone scaffold is an artificial structure used for the repairs of trabecular bones damaged by injuries or degenerative diseases. In bone-tissue engineering a proper description of its deformation behaviour is one of the most important characteristics for an assessment of the biocompatibility and bone-integration characteristics of the proposed structure intended to be used as a bone scaffold. According to recent studies bioactive-glass-reinforced gellan-gum (GG-BAG) is a promising material for bone-scaffold production. However, its low specific stiffness and simultaneous low attenuation to X-rays makes both the mechanical and imaging parts of the deformation experiments difficult. As a result a state-of-the-art experimental setup composed of high-precision micro-loading apparatus designed for the X-ray observation of deformation processes and an advanced radiographical device is required for such experiments. Furthermore, the radiographical device has to utilize highly sensitive detectors and corresponding radiation sources with appropriate beam characteristics that provide a high signal-to-noise ratio (SNR) during all the measurements. High-resolution time-lapse micro-focus X-ray computed tomography (micro-CT) under loading in three different imaging modes was performed to obtain a precise structural and mechanical description of the observed deforming GG-BAG scaffolds. The digital volumetric correlation (DVC) method was applied on reconstructed data from micro-CT measurements to evaluate not only the effective mechanical characteristics but also to enable a detailed inspection of the specimens’ internal structure, particularly the deformation modes of the individual struts and joints. The calculated volumetric strain fields demonstrate the suitability of such experimental methodology and devices for the assessment of both the microscopic and macroscopic characteristics of the investigated complex GG-BAG microarchitectures.

Keywords: bone scaffold, gellan gum, time-lapse micro-CT, digital volume correlation
1 INTRODUCTION

To successfully develop an artificial bone scaffold various fundamental requirements have to be fulfilled: i) the provision of normal cellular activity without potential toxicity, ii) the minimization of potential stress shielding effects, iii) the reliable long-term supply of organic/anorganic nutrients and oxygen and iv) the controlled progressive degradation and resorption of the scaffold during healing.1 Apparently, these requirements also closely comply with the general goals of modern bone-tissue engineering. However, in contrast to established materials for bone-tissue engineering (particularly HAP) the usage of GG-BAG for scaffold production may significantly reduce the potential for complications due to various influences, including donor site morbidity, limited availability, immune rejection and pathogen transfer.2 Here, the successful application of a GG-BAG-based scaffold allows healing of the bone, even in the case of its partial amputation, supports natural formation of bone tissue according to stress fields and thus full restoration of the bone’s primary function – the provision of mechanical support.

High-resolution time-lapse micro-focus X-ray computed tomography (micro CT) is currently the only feasible method for an investigation of volumetric deformation processes of micro-structural materials and specimens during loading.3 Moreover, due to the very complex, spontaneously synthesized, stochastic scaffold microarchitecture description of its mechanical properties based on the overall characteristics appears to be insufficient. In the presented work a custom-designed experimental setup allowing the performance of mechanical testing during radiographical imaging is employed to evaluate detailed volumetric strain fields in the deforming scaffolds’ microstructure using digital volumetric correlation (DVC).4

2 MATERIALS AND METHODS

2.1 Bioactive-glass-reinforced gellan-gum scaffolds

The recently proposed bioactive-glass-reinforced gellan-gum (GG-BAG), which is a promising material for bone scaffold fabrication, was used in this study.5 Gellan-gum (GG) is a microbial extracted polysaccharide used in the food and pharmaceutical industries.6,7 GG is composed of repeating units consisting of two D-glucose and one of each L-rhamnose and D-gluconic acid.8 Its main advantage is in an ability to form highly porous 3D structures when properly cross-linked and fabricated.9 In the field of bone regeneration the GG is biocompatible and biodegradable but it doesn’t have sufficient mechanical properties to enable successful bone regeneration and it does not promote bone formation. Therefore, GG has to be reinforced by bioactive glass particles (BAG).

BAG is a nano-particulate amorphous material with a chemical composition of 70 n/n % SiO2 and 30 n/n % CaO and it is prepared by a modified sol-gel method.10 BAG is a bioactive material and upon biodegradation there are no toxic products left behind. Therefore, BAG particles are very interesting for bone-regeneration applications.

During the production process gellan gum was dissolved in ultra-pure water by heating the solution for 30 °C min at 90 °C. To the hot GG solution a dispersion of BAG was admixed and 0.18 w/w % CaCl2 was added. Kept at high temperatures this mixture was then poured into the required mould and let there to spontaneously jellify. The weight ratio between GG and BAG was 1:1 and the final concentration of CaCl2 was 0.03 w/w % in all samples. Such samples were frozen 12 h at −80 °C and freeze-dried for 3 d in Lio 5 freeze dryer Kambič.5

Table 1: Dimensions and weights of the samples subjected to mechanical testing

<table>
<thead>
<tr>
<th>Specimen 1</th>
<th>Specimen 2</th>
<th>Specimen 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weight (mg)</td>
<td>11.2</td>
<td>10.4</td>
</tr>
<tr>
<td>Width (mm)</td>
<td>5.95-6.20</td>
<td>5.89-6.28</td>
</tr>
<tr>
<td>Height (mm)</td>
<td>6.04-6.08</td>
<td>6.54-6.62</td>
</tr>
<tr>
<td>BAG</td>
<td>no</td>
<td>no</td>
</tr>
</tbody>
</table>

Table 1: Dimenzije in masa vzorcev za mehanske preizkuse

<table>
<thead>
<tr>
<th>CT measurement</th>
<th>Photon counting detector, continual loading</th>
<th>Photon counting detector, discrete loading steps</th>
<th>Flat panel detector, discrete loading steps</th>
</tr>
</thead>
</table>

Figure 1: SEM micrograph of the scaffold obtained by scanning electron microscopy

Slika 1: SEM-posnetek celičnega ogrodja
Dimensions and weights of the three scaffolds manufactured from GG are presented in Table 1, and details of their microstructure is shown in Figure 1.

2.2 Mechanical testing

Compression tests of the GG-BAG samples were performed using a custom-designed uni-axial loading device. The device was designed to be suitable for mechanical testing of materials during continuous observation using X-rays including computed micro-tomography. Therefore, the main frame of the device is made of transparent polymethyl methacrylate tube with a 5.0 mm wall thickness and negligible X-ray attenuation. The loading mechanism consists of a stepper motor, flexible coupling, planetary gear unit P42-25 (Transtecno, Italy) and translation stage with micro-metric screw 7T173-20 (Standa, Lithuania). Such a mechanism is able to stress the specimen with a loading speed of 0.1–20 μm s⁻¹ with an experimentally measured movement accuracy of better than 5 μm. The loading procedure is controlled by a GNU/Linux real-time operational system. In the case of scaffold measurements the device was equipped with a high-accuracy load cell and a 50-N load capacity HBM U9C (HBM, Germany).

2.3 Radiographical imaging

X-ray imaging of the compression tests was carried out using a modular X-ray setup with cone-beam tomography arrangement. As the GG-BAG material has very a low attenuation of X-rays three different scanning approaches were employed to find the best settings for the scaffold imaging. Conventional scanning at discrete loading steps using a flat panel detector was selected as a first option. Scanning using a photon counting detector in discrete loading steps was selected as a second option and a continuous fast tomography measurement (without loading steps) using a photon counting detector as a third option. In all cases the X-ray beam was generated by micro-focus X-ray tube with reflection target (XWT-240-SE, X-Ray Worx, Germany) operated at 50 kV, a 500 μA target current and a focal spot size of 5 μm. X-ray images of sample 3 were taken using a large area flat panel scintillating detector (Perkin Elmer XRD 1622 AP, USA) with an effective resolution of 2048 x 2048 px. The setup geometry was adjusted to 1230 mm focus-detector distance and 123 mm focus-object distance. Therefore, planar X-ray images resulted in 10x magnification and a 20 μm pixel size. One highly detailed tomography of the undeformed specimen (1200 projections) and three regular tomography scans (800 projections) at three different loading steps were taken. For scanning of another two samples (sample 1 and sample 2) a modular photon-counting detector consisting of 2x2 TimePIX chips with fast read-out (the ModuPIX detector) and an effective resolution of 1024 x 1024 px was employed. As a photon-counting detector and fast tomography requires an X-ray beam with high intensity the focus-detector distance was reduced to 175.5 mm and the focus-object distance was reduced to 95 mm. Thus, planar X-ray images in the case of imaging using photon counting detector resulted in 1.84x magnification and 30 μm pixel size. Sample 2 was scanned in 6 discrete loading steps. A total of 600 projections were acquired in each tomography measurement. Sample 1 was loaded continuously with 0.1 μm.s⁻¹ loading speed and several tomography scans were taken with no time separation. In this case 400 projections were acquired in each tomography and one CT scan lasted approx. 4.5 min. The specimen was compressed by approximately 30 μm displacement during one CT scan (approx. 1 pixel in X-ray images). Linearization of the attenuation range (beam hardening correction) was applied to all the data to reduce the noise and improve the contrast in individual projections. Due to high porosity of the samples and the small thickness of the structural elements (approximately 30 μm), the cone-beam reconstruction algorithm was used to eliminate the distortion of the reconstructed data caused by the divergent nature of the X-ray beam. The setup for radiographical imaging is shown in Figure 2.

Figure 2: Micromorphological setup arrangement
Slika 2: Mikromorfologski sestav
2.4 Deformation mapping using digital volume correlation

The digital volumetric correlation (DVC) technique is a suitable tool for an evaluation of displacements and strains within the entire volume of the samples. The method makes it possible to track the changes in a sequence of volumetric images and to calculate the displacement of nodes representing the microstructure of the investigated samples. DVC uses the maximisation approach to find the correlation coefficient for the best fit between sub-image data defined around control points established in the reference image data. The correlation coefficient is evaluated by examining the pixel intensity of the image subsets in the corresponding image data and then the deformation mapping function is extracted. To maximise the correlation coefficient a nonlinear optimisation technique and an iterative approach were used. Coefficients of the linear affine transformation between the undeformed and deformed states can be used to establish the components of the displacement vector and the components of the gradient tensor. Then, using the deformation gradient tensor \( F \), it is possible to calculate the Green-Lagrangian strain tensor as Equation (1):

\[
E = F^TF - I
\]

The calculation of the inner deformation of the samples in all the loading states was performed using the custom DVC algorithm implemented in Matlab. Due to the computational complexity only two mutually perpendicular vertical planes passing through the centre of each sample were used for the displacement calculations. It was assumed that the displacement of the nodes in these planes sufficiently describes the deformation behaviour of the whole sample. The initial position of the tracked nodes corresponding to these planes was selected on the basis of detailed voxel model of each sample in the intact state.

3 RESULTS AND DISCUSSION

Three samples were subjected to compressive loading using a uni-axial loading device and the deformation behaviour of the inner structure was captured using X-ray imaging technique. Samples 2 and 3 were loaded in several successive phases (between the phases the tomography of sample was performed) while sample 1 was loaded continuously with a 0.1 μm s⁻¹ loading speed. Stress-strain curves of these loading tests are shown in Figure 3. In the case of samples 2 and 3 it is clearly apparent that considerable relaxation of the samples (sudden decrease in stress value) occurred during the tomographic imaging. On the other hand, the stress-strain curve of sample 1 is not affected by the relaxation process because the tomographic imaging was performed during the loading process and the load applied to the sample was continuously incremented without interruption. The small repetitive decreases of the stress value visible on the stress-strain curve in this case are not a relaxation of the sample but were caused by the technical limitations of the experimental setup. As the loading device is equipped with supply cables the rotation stage with the loading device had to be returned to the initial position and the vibration of the rotation table during the homing sequence caused the micro-movement of the sample.

As expected the stiffness of sample 3 was higher than in case of non-reinforced samples 1 and 2. A mutual comparison of the response of non-reinforced samples 1 and 2 shows large difference of stiffness presumably...
caused by the different nature of the spontaneously synthesized inner structure. Because of the complex inner structure of the scaffolds the overall (effective) strain assessed from the movement of the loading platens is not a reliable parameter for characterising the deformation behaviour of such a material. Therefore, an advanced strain calculation based on the DVC technique was used in the study.

The DVC algorithm is extensively time-consuming and its computational cost linearly increases with the number of calculated deformation states. For this reason, only the displacement of nodes belonging to two mutually perpendicular vertical planes located in the centre of each sample were used (for sample 3 only one plane was used). These planes (YZ and XZ orientation) included: 14,720 nodes and 19,790 nodes for sample 1; 24,452 nodes and 23,076 nodes for sample 2; 46,728 nodes for sample 3. A larger number of nodes in the case of sample 3 relates to higher resolution of the flat panel detector. During the parallel DVC calculation (4 threads of Intel i7-3820 CPU) the displacement vector of each node in the selected plane through all the loading states was determined. Green-Lagrangian strain of every voxel was evaluated on the basis of displacement vectors of its corresponding nodes. Fields of the vertical displacement and the evaluated strain for one plane of each sample in selected deformation states mapped on the structure of the intact state are shown in Figures 4 to 6. The obtained deformation and strain fields show that the DVC technique can be successfully used for a determination of such complex deformation processes. As can be seen from the results the deformation of the samples was not limited only to uni-axial compression, as anticipated, but apparent bending of the samples caused by their complex inner structure, improper boundary conditions and sample geometry was present. Despite our best efforts, it was not possible to manufacture the samples with plan-parallel top and bottom faces. The evaluation of the elastic parts of the resulting stress-strain curves also showed the reason for the lower stiffness of the sample 1 when compared to the sample 2. As can be seen in Figure 6 the struts of the inner structure of the sample 1 are oriented perpendicularly to the applied load while the struts of the inner structure of sample 2 (Figure 5) are mainly oriented in the direction of loading.

4 CONCLUSIONS

In this work the demonstration of modern radiological and computational methods for the investigation of the deformation behaviour of artificial bone scaffolds was shown.

Three samples were loaded using a custom uni-axial compression device and tomographically scanned in three different loading scenarios: i) flat panel scintillating detector with incremental loading steps, ii) fast photon-counting detector with incremental loading steps and iii) fast photon-counting detector with continuous loading. In the case of incrementally applied loading divided into individual steps the relatively large relaxa-
tion of the sample was observed during the tomography scanning. This undesirable relaxation process was eliminated in a scenario with continuous loading, which was made possible by the advantageous characteristics of the single photon-counting detectors, the fast readout speed and very high signal-to-noise ratio. Although the number of tomographic projections during continuous loading was halved compared to other scenarios the reconstructed tomographic data still had sufficient quality for a reliable DVC calculation. This fact clearly demonstrates the suitability of the photon-counting detector for the imaging of samples with a low attenuation of X-rays. Future work will be focused on improvements to the parameters of the compression test with continuously performing tomography using a fast photon-counting detector to obtain precise data for calculation of the mechanical characteristic of scaffold as well as speeding up the measurement.

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